

MSSL Advanced Theory Lectures

General Relativity - Problem Sheet 1

Question 1

Which of the following tensor equations are valid, and which are not? Describe the errors in those which are not valid.

$$\begin{aligned} K &= R_{abcd}R^{abcd} \\ F_{ab} &= T_{ac}T^c_{\quad cd} + \frac{1}{4\pi}g^{ab}T_{ab}T^{ab} \\ Q &= g_{ab}U^aU^b \end{aligned}$$

Question 2

Consider the type $\binom{2}{0}$ tensor T^{ab} acting in a 4-dimensional manifold (i.e. a, b range from $(0, 1, 2, 3)$, T^{ab} being a 4×4 matrix). How many independent components does T^{ab} have in general? How many independent components do the symmetric and antisymmetric parts $T^{(ab)}$ and $T^{[ab]}$ have? Hence, confirm that a general tensor can be decomposed into a symmetric and an antisymmetric part.

Question 3

Prove the following vector identities

$$\nabla \times \nabla \phi = 0, \tag{1}$$

$$\nabla \cdot (\nabla \times \bar{a}) = 0, \tag{2}$$

$$\nabla \times (\psi \bar{a}) = \nabla \psi \times \bar{a} + \psi \nabla \times \bar{a}, \tag{3}$$

$$\nabla \cdot (\phi \bar{a}) = \phi \nabla \cdot \bar{a} + \bar{a} \cdot \nabla \phi, \tag{4}$$

$$\nabla \times (\bar{a} \times \bar{b}) = \bar{a}(\nabla \cdot \bar{b}) - \bar{b}(\nabla \cdot \bar{a}) + (\bar{b} \cdot \nabla)\bar{a} - (\bar{a} \cdot \nabla)\bar{b}. \tag{5}$$

Question 4

Consider the metric for 3-dimensional flat Euclidean space

$$ds^2 = dx^2 + dy^2 + dz^2. \tag{6}$$

Oblate spheroidal coordinates are related to Cartesian coordinates via the transformation

$$x = \sqrt{r^2 + a^2} \sin \theta \cos \phi, \tag{7}$$

$$y = \sqrt{r^2 + a^2} \sin \theta \sin \phi, \tag{8}$$

$$z = r \cos \theta. \tag{9}$$

Show that the metric in this new coordinate system is given by

$$ds^2 = \frac{\Sigma}{\Delta} dr^2 + \Sigma d\theta^2 + \Delta \sin^2 \theta d\phi^2, \tag{10}$$

where

$$\Sigma = r^2 + a^2 \cos^2 \theta, \tag{11}$$

$$\Delta = r^2 + a^2. \tag{12}$$

What happens as $a \rightarrow 0$?

Question 5

Solve the geodesic equations of motion for the following two metrics

$$ds^2 = dx^2 + dy^2 + dz^2, \quad (13)$$

$$ds^2 = dr^2 + r^2 d\phi^2 + dz^2. \quad (14)$$

What do the solutions imply? Compute the non-zero Christoffel symbols for (14).

Question 6

Show that the line element

$$ds^2 = g_{ab} dX^a dX^b, \quad (15)$$

is a scalar, i.e. determine how ds^2 transforms under general coordinate transformations.

Note: It may prove easier to use the following notation for transformation laws for contravariant and covariant vectors

$$V^{a'} = \frac{\partial X^{a'}}{\partial X^a} V^a, \quad (16)$$

$$W_{b'} = \frac{\partial X^b}{\partial X^{b'}} W_b, \quad (17)$$

from now on, which can easily be generalised to tensors. This notation will simplify the working in later questions.

(Hint: Consider how $g_{a'b'} dX^{a'} dX^{b'}$ transforms under general coordinate transformations)

Question 7

Demonstrate how

$$A^b_{,a} \equiv \partial_a A^b$$

transforms under general coordinate transformations. Is $A^b_{,a}$ a tensor? In General Relativity, as in tensor analysis, what property must a good operator possess? Should this be used as a partial derivative operator in General Relativity?

Question 8 (Challenging)

Recall the Christoffel symbol from the lectures, also known as the affine connection. We have already mentioned in lecture 2 that in moving from flat space to General Relativity and curved spacetimes

$$\partial_a \rightarrow \nabla_a,$$

namely that the partial derivative now becomes a *covariant* derivative operator. Given the result of question 7, the covariant derivative operator ∇_a (being inherently covariant) must be composed of the partial derivative operator ∂_a and a correction term (given spacetime is no longer flat), which can be expressed in terms of the affine connection Γ^a_{bc} , namely

$$\nabla_a V^b = \partial_a V^b + \Gamma^b_{ac} V^c. \quad (18)$$

Using the above expression for the covariant derivative, show that the Christoffel symbol transforms as

$$\Gamma^{a'}_{b'c'} = \frac{\partial X^c}{\partial X^{c'}} \frac{\partial X^b}{\partial X^{b'}} \frac{\partial X^{a'}}{\partial X^a} \Gamma^a_{bc} - \frac{\partial X^b}{\partial X^{b'}} \frac{\partial X^c}{\partial X^{c'}} \frac{\partial^2 X^{a'}}{\partial X^b \partial X^c}. \quad (19)$$

What does this tell us about the Christoffel symbol, and why?

Question 9

In General Relativity the most general static, spherically symmetric metric is given by

$$ds^2 = -e^{\nu(r)} dt^2 + e^{\lambda(r)} dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2. \quad (20)$$

Compute the non-zero Christoffel symbols for this metric (9 in total).

Question 10

Working with the Minkowski signature convention $(+, -, -, -)$, for a given scalar potential ϕ and vector potential $\bar{\mathbf{A}}$ the 4-potential A^a can be defined as $A^a = \begin{pmatrix} \phi \\ \bar{\mathbf{A}} \end{pmatrix}$, $A_a = \eta_{ab} A^b = (\phi, -\bar{\mathbf{A}})$. From the definition of the magnetic and electric field

$$\bar{\mathbf{B}} = \nabla \times \bar{\mathbf{A}}, \quad (21)$$

$$\bar{\mathbf{E}} = -\nabla\phi - \partial_t \bar{\mathbf{A}}, \quad (22)$$

and the Faraday tensor

$$F_{ab} = A_{b,a} - A_{a,b}, \quad (23)$$

show explicitly that in Cartesian coordinates the Faraday tensor is given by

$$F_{ab} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{bmatrix}, \quad (24)$$

where (a, b) run over (t, x, y, z) . The dual Faraday tensor is defined as

$$*F^{ab} = \frac{1}{2} \varepsilon^{abcd} F_{cd}, \quad (25)$$

where ε^{abcd} is the Levi-Civita symbol, defined in lecture 1. Show explicitly that

$$*F^{ab} = \begin{bmatrix} 0 & -B_x & -B_y & -B_z \\ B_x & 0 & E_z & -E_y \\ B_y & -E_z & 0 & E_x \\ B_z & E_y & -E_x & 0 \end{bmatrix}. \quad (26)$$

Furthermore, show that

$$*F_{ab} F^{ab} = 4(\bar{\mathbf{B}} \cdot \bar{\mathbf{E}}), \quad (27)$$

$$F_{ab} F^{ab} = 2(\mathbf{B}^2 - \mathbf{E}^2). \quad (28)$$

If you recall how to find the determinant of a 4×4 matrix then show that

$$\det(F) = (\bar{\mathbf{B}} \cdot \bar{\mathbf{E}})^2, \quad (29)$$

which also holds for the dual Faraday tensor. (Hint: $F^{ab} \leftrightarrow F_{ab} \implies \bar{\mathbf{E}} \leftrightarrow -\bar{\mathbf{E}}, \bar{\mathbf{B}}$ fixed)